

CHAPTER 8e. DIFFERENTIAL EQUATIONS



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by

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ENCE 203 - Computation Methods in Civil Engineering II

Department of Civil and Environmental Engineering

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First-order Ordinary Differential Equations



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■ Galerkin Method

Procedure for Deriving Galerkin Approximating Polynomial

1. For a given ordinary differential equation, assume that the solution is a differentiable function such as given by the following polynomial:

$$\hat{y} = b_0 + b_1x + b_2x^2 + \dots + b_nx^n \quad (29)$$



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■ Galerkin Method

2. Use the boundary condition of the ordinary differential equation to evaluate one of the coefficients of the assumed function or to provide a condition toward the solution of the coefficients.
3. Provide an expression for the error e as

$$e = \frac{d\hat{y}}{dx} - \frac{dy}{dx} \quad (30)$$



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■ Galerkin Method

4. Compute the weight w_i for each coefficient, where

$$w_i = \frac{d\hat{y}}{db_i} \quad (31)$$

5. The normal equations are computed from

$$\int_x w_i e \, dx = 0 \quad \text{for } i = 1, 2, \dots, n \quad (32)$$



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Example 15 – Galerkin Method

Using the Galerkin method with a linear model (i.e. $\hat{y} = b_0 + b_1x$) and for $0 \leq x \leq 1$ to find an approximating function for the following differential:

$$\frac{dy}{dx} = xy \quad \text{such that } y = 1 \text{ at } x = 0$$

Using this function, estimate y at $x = 0.6$ and compare with the true value.



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Example 15 (cont'd) – Galerkin Method

$$\hat{y} = b_0 + b_1x$$

$$\hat{y}(0) = 1 = b_0 + b_1(0) \Rightarrow b_0 = 1$$

$$e = \frac{d\hat{y}}{dx} - \frac{dy}{dx}$$

$$\hat{y} = 1 + b_1x \quad \text{and} \quad \frac{d\hat{y}}{dx} = b_1$$



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Example 15 (cont'd) – Galerkin Method

$$\frac{dy}{dx} = xy \quad (\text{given by the DE})$$

$$e = \frac{d\hat{y}}{dx} - \frac{dy}{dx} = b_1 - xy = b_1 - x(1 - b_1x)$$

$$w_1 = \frac{d\hat{y}}{db_1} = x$$



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Example 15 (cont'd) – Galerkin Method

$$\int_0^1 w_1 e \, dx = \int_0^1 x [b_1 - x(1 - b_1x)] \, dx = 0$$

$$\int_0^1 [xb_1 - x^2 + b_1x^3] \, dx = 0$$

$$\left. \frac{x^2b_1}{2} - \frac{x^3}{3} + \frac{x^4b_1}{4} \right|_0^1 = \frac{b_1}{2} - \frac{1}{3} + \frac{b_1}{4} = 0$$

$$\frac{3b_1}{4} = \frac{1}{3} \Rightarrow b_1 = \frac{4}{9}$$



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Example 15 (cont'd) – Galerkin Method

Therefore the approximating function (linear polynomial) is given by

$$\hat{y} = b_0 + b_1x = 1 + \frac{4}{9}x$$

$$\text{and } \hat{y}(0.6) = 1 + \frac{4}{9}(0.6) = 1.2667$$

The true value is given by

$$y(0.6) = e^{x^2/2} = e^{(0.6)^2/2} = 1.1972$$

$$\text{error (\%)} = \left| \frac{1.1972 - 1.2667}{1.1972} \right| \times 100 = 5.8\%$$



Higher-order Differential Equations

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- Many engineering problems require the solution of higher-order differential equations.
- For example a second-order differential equation can be given as

$$\frac{d^2y}{dx^2} = f\left(x, y, \frac{dy}{dx}\right) \quad (33)$$



Higher-order Differential Equations

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- The function $f(\cdot)$ does not need to include all the parameters x , y , and dy/dx .
- Examples of higher-order differential equations are

$$\frac{d^2 y}{dx^2} = 2x \quad \text{such that } y = 0 \text{ and } \frac{dy}{dx} = 0 \text{ at } x = 0$$

$$\frac{d^3 y}{dx^3} - 2x - yx + 4 = 0$$



Higher-order Differential Equations

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- The methods previously introduced can be used to solve higher-order differential equations after transforming them into systems of first-order differential equations.
- The procedure for transforming the DE's for the following example is as follows:



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$$\frac{d^2 y}{dx^2} = f\left(x, y, \frac{dy}{dx}\right)$$

becomes

$$\frac{dy_2}{dx} = f(x, y, y_2)$$

$$\frac{dy_1}{dx} = y_2 \quad \text{where } y_1 = y_2$$

$$y_2 = \frac{dy_1}{dx} = \frac{dy}{dx}$$



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Higher-order Differential Equations

$$\frac{dy_1}{dx} = f_1(x, y_1, y_2, \dots, y_n)$$

$$\frac{dy_2}{dx} = f_2(x, y_1, y_2, \dots, y_n) \quad (34)$$

⋮

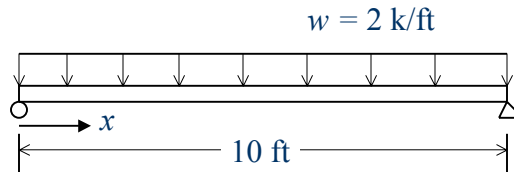
$$\frac{dy_n}{dx} = f_n(x, y_1, y_2, \dots, y_n)$$



Higher-order Differential Equations

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Example – Simply Supported Beam



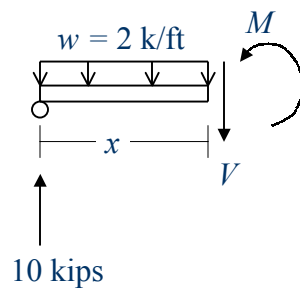
$$\frac{d^2 y}{dx^2} = \frac{M(x)}{EI}$$



Higher-order Differential Equations

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Example (cont'd) – Simply Supported Beam



$$\sum M = -M + 10x - 2x\left(\frac{x}{2}\right) = 0$$

$$-M + 10x - x^2 = 0$$

$$M = 10x - x^2$$



Higher-order Differential Equations

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Example – Simply Supported Beam

Let

$$\theta = \frac{dy}{dx} = \text{rotation}$$

$$\frac{d^2y}{dx^2} = \frac{d\theta}{dx} = \frac{M(x)}{EI}$$

Hence

$$\frac{d\theta}{dx} = \frac{10x - x^2}{EI}$$

$$\frac{dy}{dx} = \theta$$



Higher-order Differential Equations

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Example (cont'd) – Simply Supported Beam

Assume that $EI = 3600 \text{ kip/ft}^2$ and at $x = 0$, $y = 0$ and $\theta = -0.02314$, and $h = 0.1$.

Using basic Euler's method for example, the following equations result:

$$\theta_{i+1} = \theta_i + f_{\theta}(x_i, y_i, \theta_i)h$$

$$y_{i+1} = y_i + f_y(x_i, y_i, \theta_i)h$$



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- Example (cont'd) – Simply Supported Beam
First Iteration ($i = 0$)

$$x_0 = 0, \theta_0 = -0.02314, \text{ and } y = 0$$

$$f_\theta(x_i, \theta_i, y_i) = f_\theta(x_0, \theta_0, y_0) = \left. \frac{d\theta}{dx} \right|_{\substack{x=x_0 \\ \theta=\theta_0 \\ y=y_0}} = \frac{10x - x^2}{EI}$$

$$f_\theta(0, -0.0231481, 0) = \frac{10(0) - (0)^2}{3600} = 0$$

$$\theta_1 = \theta_0 + f_\theta(0, -0.0231481, 0)h$$

$$\theta_1 = -0.0231481 + 0 = -0.0231481$$

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- Example (cont'd) – Simply Supported Beam

$$f_y(x_i, \theta_i, y_i) = f_y(x_0, \theta_0, y_0)h = \frac{dy}{dx} = \theta_0$$

$$f_y(0, -0.0231481, 0) = \theta_0 = -0.0231481$$

$$y_1 = y_0 + f_y(x_0, \theta_0, y_0)h$$

$$= y_0 + f_y(0, -0.0231481, 0)$$

$$y_1 = 0 - 0.0231481(0.1) = -0.00231481$$

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- Example (cont'd) – Simply Supported Beam
Second Iteration ($i = 1$)

$$x_1 = 1.1, \theta_1 = -0.02314, \text{ and } y = -0.00231481$$

$$f_\theta(x_i, \theta_i, y_i) = f_\theta(x_1, \theta_1, y_1) = \left. \frac{d\theta}{dx} \right|_{\substack{x=x_1 \\ \theta=\theta_1 \\ y=y_1}} = \frac{10x - x^2}{EI}$$

$$f_\theta(0.1, -0.0231481, -0.00231481) = \frac{10(0.1) - (0.1)^2}{3600} = 0.00025$$

$$\theta_2 = \theta_1 + f_\theta(0.1, -0.0231481, -0.00231481)h$$

$$\theta_2 = -0.0231481 + 0.000275(0.1) = -0.0231206$$

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- Example (cont'd) – Simply Supported Beam

$$f_y(x_i, \theta_i, y_i) = f_y(x_1, \theta_1, y_1)h = \frac{dy}{dx} = \theta_1$$

$$f_y(0.1, -0.0231206, 0) = \theta_1 = -0.0231206$$

$$y_2 = y_1 + f_y(x_1, \theta_1, y_1)h$$

$$= y_1 + f_y(0, -0.0231206, 0)$$

$$y_2 = -0.00231481 - 0.0231206(0.1) = -0.0046269$$

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Example (cont'd) – Simply Supported Beam

The exact solution is given by

$$\theta = \left(5x^3 - \frac{x^3}{3}\right) \frac{1}{3600} - 0.0231481$$

$$y = \left(\frac{5x^3}{3} - \frac{x^4}{12}\right) \frac{1}{3600} - 0.0231481x$$

x (ft)	$\frac{d\theta}{dx}$	$\theta = \frac{dy}{dx}$	y (ft)	Exact θ	Exact y (ft)
0	0	-0.0231481	0	-0.0231481	0
0.1	0.0002750	-0.0231481	-0.0023148	-0.0231343	-0.0023143
0.2	0.0005444	-0.0231206	-0.0046296	-0.0230933	-0.0046260
0.3	0.0008083	-0.0230662	-0.0069417	-0.0230256	-0.0069321
0.4	0.0010667	-0.0229853	-0.0092483	-0.0229318	-0.0092302
0.5	0.0013194	-0.0228787	-0.0115468	-0.0228125	-0.0115176
0.6	0.0015667	-0.0227467	-0.0138347	-0.0226681	-0.0137919
0.7	0.0018083	-0.0225900	-0.0161094	-0.0224993	-0.0160504
0.8	0.0020444	-0.0224092	-0.0183684	-0.0223066	-0.0182909
0.9	0.0022750	-0.0222048	-0.0206093	-0.0220906	-0.0205110
1	0.0025000	-0.0219773	-0.0228298	-0.0218518	-0.0227083
2	0.0044444	-0.0185564	-0.0434304	-0.0183333	-0.0429629
3	0.0058333	-0.0134412	-0.0598018	-0.0131481	-0.0588193
4	0.0066667	-0.0071870	-0.0704996	-0.0068518	-0.0688887
5	0.0069444	-0.0003495	-0.0746349	0.0000000	-0.0723377
6	0.0066667	0.0065158	-0.0718744	0.0068519	-0.0688886
7	0.0058333	0.0128533	-0.0624403	0.0131482	-0.0588191
8	0.0044444	0.0181075	-0.0471104	0.0183334	-0.0429626
9	0.0025000	0.0217227	-0.0272179	0.0218519	-0.0227079
10	0.0000000	0.0231436	-0.0046518	0.0231482	0.0000000

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Boundary-Value Problems

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- The previous methods for solving ordinary differential equations can be used to solve higher-order differential equations as discussed earlier.
- These methods require the initial conditions to be at the same x value.

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Boundary-Value Problems

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- For example, the initial conditions in Example 15 were given as

$$x_0 = 0$$

$$y_0 = 0$$

$$\theta_0 = -0.0231481$$

- The rotation θ is not usually known.
- However, in Ex. 15 it is known that at $x = 0, y = 0$ and at $x = 10, y = 0$



Boundary-Value Problems

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- The two conditions have different x values. Therefore, they cannot be used in solving the differential equation based on the previous methods.
- In this case, we are dealing with a boundary-value problem.
- Boundary-value problems can be solved numerically using Shooting and Finite-difference methods.



Boundary-Value Problems

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■ Shooting Method

- The shooting method is a trial-and-error method that uses any of the previously introduced methods for solving differential equations.
- The shooting method is based on converting the boundary-value problem into an equivalent initial-value problem.



Boundary-Value Problems

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■ Finite-Difference Method

Recall the finite-difference expressions for approximating the first and second derivatives based on two-step method

$$f'(x_i) \approx \frac{f(x_{i+1}) - f(x_i)}{2h} \quad (35)$$

$$f''(x_i) \approx \frac{f(x_{i-1}) - 2f(x_i) + f(x_{i+1}))}{h^2} \quad (36)$$



Boundary-Value Problems

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- Finite-Difference Method
 - In this method, the derivatives in the differential equation are replaced by finite-difference equations (formulas).
 - Then, the resulting DE, which is now in a finite-difference form, is used at some interior points using a selected step size h and the boundary conditions.



Boundary-Value Problems

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- Finite-Difference Method
 - Each use of the finite-difference equation results in a linear equation in terms of the unknown solutions at the selected interior points.
 - In this case, we get a system of linear equations that need to be solved simultaneously to obtain the solution at the interior points.

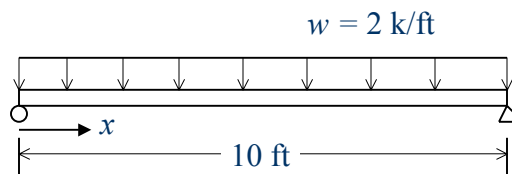


Boundary-Value Problems

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Example 16 – Simply Supported Beam

The simply supported beam is subjected to distributed loading w as shown in the figure. Numerically, find the bending moment M at each node along its span.



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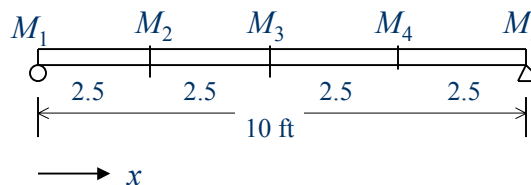
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Example 16 – Simply Supported Beam

B.C.'s:

$$\text{at } x = 0, M = 0$$

$$\text{and at } x = 10, M = 0$$



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Boundary-Value Problems

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- Example 16 (cont'd) – Simply Supported Beam

The governing differential equation in this case is given by

$$\frac{d^2 M}{dx^2} = w = \text{distributed load}$$

or

$$\frac{d^2 M}{dx^2} = -2$$



Boundary-Value Problems

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- Example 16 (cont'd) – Simply Supported Beam

$$f''(x_i) \approx \frac{f(x_{i-1}) - 2f(x_i) + f(x_{i+1}))}{h^2} \quad (\text{Eq. 36})$$

The original differential equation can be converted to a finite-difference equation (see Eq. 36) as follows:

$$\frac{d^2 M}{dx^2} \approx \frac{M_{i-1} - 2M_i + M_{i+1}}{h^2}$$

$$\frac{M_{i-1} - 2M_i + M_{i+1}}{h^2} = -2 \quad (37)$$



Boundary-Value Problems

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Example 16 (cont'd) – Simply Supported Beam

h , in case, is equal to 2.5 ft, therefore Eq. 37 can be simplified as follows.

$$\frac{M_{i-1} - 2M_i + M_{i+1}}{(2.5)^2} = -2$$

OR

$$M_{i-1} - 2M_i + M_{i+1} = -2(6.25)$$

$$M_{i-1} - 2M_i + M_{i+1} = -12.5 \quad (38)$$



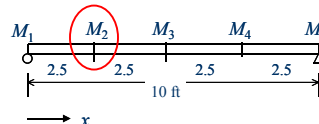
Boundary-Value Problems

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Example 16 (cont'd) – Simply Supported Beam

Application of Eq. 38 at the interior nodes 2, 3, and 4, yields a set of three simultaneous equations as follows:

At Node 2:



$$M_1 - 2M_2 + M_3 = -12.5$$

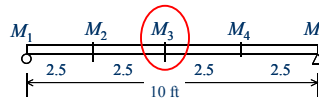


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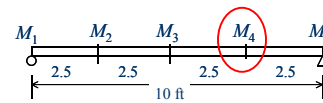
- Example 16 (cont'd) – Simply Supported Beam

At Node 3:



$$M_2 - 2M_3 + M_4 = -12.5$$

At Node 4



$$M_3 - 2M_4 + M_5 = -12.5$$

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- Example 16 (cont'd) – Simply Supported Beam

$$-2M_2 + M_3 = -12.5$$

$$M_2 - 2M_3 + M_4 = -12.5$$

$$M_3 - 2M_4 = -12.5$$



$$\begin{bmatrix} -2 & 1 & 0 \\ 1 & -2 & 1 \\ 0 & 1 & -2 \end{bmatrix} \begin{bmatrix} M_2 \\ M_3 \\ M_4 \end{bmatrix} = \begin{bmatrix} -12.5 \\ -12.5 \\ -12.5 \end{bmatrix} \quad (39)$$

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Boundary-Value Problems

- Example 16 (cont'd) – Simply Supported Beam

Equation 39 yields the solution as follows:

$$\begin{bmatrix} M_2 \\ M_3 \\ M_4 \end{bmatrix} = \begin{bmatrix} 18.75 \\ 25.00 \\ 18.75 \end{bmatrix} \text{ ft - kips}$$



☺

I wish you good luck
in your final ☺
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